

# **VLT® Synchronizing Controller MCO 350** Option for VLT® AutomationDrive



The Synchronizing Controller MCO 350 is fully integrated in the VLT® AutomationDrive. No additional wiring is required.

The VLT<sup>®</sup> Synchronizing Controller is user-friendly, enabling set-up of all parameters via the VLT<sup>®</sup> Automation-Drive Local Control Panel or via the VLT<sup>®</sup> set-up software MCT 10.

As the VLT<sup>®</sup> Synchronizing Controller is a standard product with fixed functional properties, no additional application programming is required. To make commissioning easy, a test run function is included.

In addition, the VLT® Synchronizing Controller includes the features: Choice of offset, gear ratios and read out of status.

## Synchronising on the user's terms

The technology behind the VLT® Synchronizing Controller option offers a host of user-friendly benefits for synchronising applications in many industries, like:

- Paper and plastic manufacturing
- Food and beverage processing
- Concrete and cement processing
- Bottle manufacturing

The VLT® Synchronizing Controller option for VLT® AutomationDrive expands the functional properties of the frequency converter in synchronising applications.

It replaces traditional mechanical solutions and adds new flexibility to applications like:

- Printing lines
- Bottle washers
- Conveyor belts
- Packaging and material handling systems
- Concrete vibrating machinery

Perfect
match for:

- Synchronising applications

Feature	Benefit
Innovative	
Homing	Ensures high repeatability and accuracy
<ul> <li>Hold function, speed up/down</li> <li>Four fixed gear ratios</li> <li>On-line adjustable gear ratio</li> <li>On-line adjustable position (angle) offset</li> </ul>	On the fly system adjustment
<ul> <li>Display of actual synchronising error on frequency converter control panel</li> <li>Readout of master and follower speed on frequency converter control panel</li> </ul>	Monitoring of quality and quantity made easy for the operator
<ul> <li>Speed synchronising</li> <li>Position (angle) synchronising with or without marker correction</li> </ul>	Highly flexible synchronising function, making mechanical systems redundant
Encoder output with virtual master function for synchronisation of multiple followers	Increased accuracy and repeatability of synchronisation
Auto PID calculation	Commissioning made easy





# **Technical features**

- Covers the entire series of VLT<sup>®</sup> AutomationDrive (power range 0.37–500 kW, voltage range 200 V–500 V)
- Built-in option preserves the IP/NEMA rating
- Control and status signals via I/O or fieldbus. Fieldbus requires an additional option card, the following are available: PROFIBUS, DeviceNet
- Access to VLT<sup>®</sup> and option parameters via fieldbus or the VLT<sup>®</sup> AutomationDrive control panel
- Improved encoder resolution thanks to quadrature signals
- Test run, PID optimising, measuring of marker distance
- Restoring of factory settings
- VLT<sup>®</sup> mode, open loop speed control for emergency VLT<sup>®</sup> operation
- Control of external electro mechanical brake

### **Two versions:**

The VLT<sup>®</sup> Synchronizing Controller MCO 350 is available with and without conformal coating.

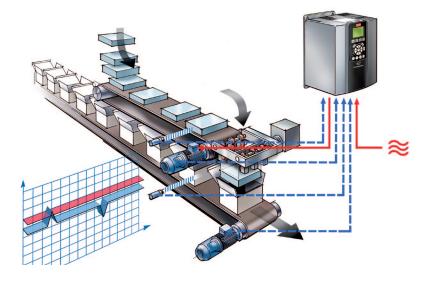
### **Option card or built-in:**

The option can be supplied either as an option card for field installation or as a built-in option in all VLT<sup>®</sup> AutomationDrives.

The VLT® AutomationDrive with Synchronizing Controller MCO 350 secures that there is always an item ready to roll off the upper (follower) conveyor when a box passes on the lower (master) conveyor, running at a fixed speed. The transportation of items and boxes is synchronised so that they move forward according to set-up. The follower is positioned in relation with the master, utilising the automatic marker correction function to align items and boxes. To control these movements, the Synchronizing Controller depends on operational data from the encoders and two position sensors.

# **Specifications**

Encoder inputsEncoder inputs2Incremental encoder specificationsIncr. encoder typeRS422/TTLMaximum frequency410 kHzPhase displacement between A and B90° ± 30°Maximum cable length300 mAbsolute encoder specifications
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Maximum frequency     410 kHz       Phase displacement between A and B     90° ± 30°       Maximum cable length     300 m
Phase displacement between A and B     90° ± 30°       Maximum cable length     300 m
Maximum cable length     300 m       Absolute encoder specifications     Image: Comparison of the specification of the s
Absolute encoder specifications
Absolute encoder type SSI
Data coding Gray
Data length 12 – 37 bit
Clock frequency 78 kHz – 2 MHz
Maximum cable length 150 m
Encoder options (B)
Sinus/cosinus
Resolver
Encoder output (virtual master)
Number of encoder outputs 1
Signal type RS422
Maximum frequency 410 kHz
Maximum number of slaves 31 (more with repeater)
Maximum cable length 400 m
Encoder voltage supply
24 V, max. load 250 mA
8 V, max. load 250 mA
5 V, max. load 400 mA
Control characteristics
Sample time of position PID loop 1 ms
Positioning static accuracy ± 1 increment
Synchronising static accuracy ± 1 increment



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